

A Survey on Riemannian Curvature Tensor for Certain Classes of Almost Contact Metric Manifolds

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ABSTRACT

This paper surveyed the components of Riemannian curvature tensor over the associated space of G-structure for certain classes of almost contact metric manifolds. These classes under consideration are only twelve and known as cosymplectic manifolds, Sasakian manifolds, Kenmotsu manifolds, C_9 -manifolds, C_{12} -manifolds, normal manifolds of Killing type (CNK-manifold), nearly Kenmotsu manifolds, locally conformal almost cosymplectic manifolds (LCAC-manifolds), quasi-Sasakian manifolds, almost $C(\lambda)$ -manifolds, nearly cosymplectic manifolds, and Kenmotsu type manifolds.

Introduction

The Riemannian curvature tensor (RC-tensor) is one of the interesting fields in the studying differential geometry. The Riemannian manifold of flat RC-tensor is locally isometric to the Euclidean space. Also, RC-tensor win its importance in the gravity theory and general relativity theory because its contraction is the Ricci tensor that a central mathematical tool in Einstein's theory. Based on the above, many authors studied RC-tensor of the manifolds and specially the almost contact metric manifolds that classified by D. Chinea and C. Gonzalez [1]. Especially among them, E. S. Volkova [2] determined the components of RC-tensor of CNK-manifolds. S. V. Umnova [3] established the components of RC-tensor of Kenmotsu manifolds and generalized Kenmotsu manifolds (nearly Kenmotsu manifolds). V. F. Kirichenko and A. R. Rustanov [4] deduced the components of RC-tensor of quasi-Sasakian manifolds. N. N. Dondukova [5].

found the components of RC-tensor of cosymplectic manifolds and Sasakian manifolds. S. V. Kharitonova [6].

Concluded the components of RC-tensor of LCAC-manifolds. V. F. Kirichenko and E. V. Kusova [7] studied the components of RC-tensor of weakly cosymplectic manifolds (nearly cosymplectic manifolds).

So, according to the previous, we summarize these results in this paper and more than ones to have a survey about the RC-tensor of almost contact metric manifolds.

Preliminaries

Definition 1. [8] A topological space M is said to be a smooth manifold of dimension n and denoted by M^n , if M is T_2 -space, second countable, locally homeomorphic to \mathbb{R}^n , and has a smooth structure.

The symbol $\mathcal{X}(M)$ denotes to the module of whole vector fields on M^n .

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Definition 2. [8] A bilinear map $g : \mathcal{X}(M) \times \mathcal{X}(M) \rightarrow \mathbb{R}$ is said to be a metric tensor on M^n , if g is symmetric and positive definite.

Definition 3. [1] If a Riemannian manifold (M^{2n+1}, g) is provided by triple of a structure tensor (Φ, η, ξ) , where η, ξ, Φ are tensors over M of types $(1, 0)$, $(0, 1)$, and $(1, 1)$ respectively, such that $\forall Z_1, Z_2 \in \mathcal{X}(M)$, the following achieved:

$$\eta(\xi) = 1; \quad \eta \circ \Phi = 0; \quad \Phi(\xi) = 0; \quad id + \Phi^2 = \eta \otimes \xi;$$

$$g(\Phi Z_1, \Phi Z_2) + \eta(Z_1)\eta(Z_2) = g(Z_1, Z_2),$$

then it is known an almost contact metric (ACM-) manifold and denoted by $(M^{2n+1}, \xi, \eta, \Phi, g)$.

Definition 4. [8] A connection on a smooth manifold M is a mapping $\nabla : \mathcal{X}(M) \times \mathcal{X}(M) \rightarrow \mathcal{X}(M)$ defined by $\nabla(Z_1, Z_2) = \nabla_{Z_1} Z_2$ and it attains the subsequent properties:

- (1) $\nabla_{f_1 Z_1 + f_2 Z_2} Z_3 = f_1 \nabla_{Z_1} Z_3 + f_2 \nabla_{Z_2} Z_3;$
- (2) $\nabla_{Z_3}(f_1 Z_1 + f_2 Z_2) = f_1 \nabla_{Z_3} Z_1 + f_2 \nabla_{Z_3} Z_2 + Z_3(f_1)Z_1 + Z_3(f_2)Z_2,$

for all $f_1, f_2 \in C^\infty(M)$ and $Z_1, Z_2, Z_3 \in \mathcal{X}(M)$.

Lemma 1. [8] Suppose that ∇ is a connection over M and $U, V \in \mathcal{X}(M)$. If $U = 0$, or $V = 0$ then $\nabla_U V = 0$.

Definition 5. [8] A Riemannian connection over the Riemannian manifold (M, g) is a connection ∇ on M that possess the following properties:

- (i) $\nabla_{Z_1} Z_2 - \nabla_{Z_2} Z_1 = [Z_1, Z_2]$, where $[Z_1, Z_2] = Z_1 \circ Z_2 - Z_2 \circ Z_1;$
- (ii) $Z_1(g(Z_2, Z_3)) = g(\nabla_{Z_1} Z_2, Z_3) + g(Z_2, \nabla_{Z_1} Z_3),$

for all $Z_1, Z_2, Z_3 \in \mathcal{X}(M)$.

There are several classes of ACM-manifolds $(M^{2n+1}, \xi, \eta, \Phi, g)$. We define some of these classes according to their Riemannian connection as the following:

Table 1. Some defining classes

Classes	Defining conditions
Cosymplectic [9]	$\nabla_{Z_1}(\Phi)Z_2 = 0$
Nearly cosymplectic [10]	$\nabla_{Z_1}(\Phi)Z_2 + \nabla_{Z_2}(\Phi)Z_1 = 0$
Kenmotsu [11]	$\nabla_{Z_1}(\Phi)Z_2 + g(Z_1, \Phi Z_2)\xi = -\eta(Z_2)\Phi Z_1$

Classes	Defining conditions
Sasakian [12]	$\nabla_{Z_1}(\Phi)Z_2 + \eta(Z_2)Z_1 = g(Z_1, Z_2)\xi$
C_9 [13]	$\nabla_{Z_1}(\Phi)Z_2 = \eta(Z_2)\nabla_{\Phi Z_1}\xi - g(\Phi Z_1, \nabla_{Z_2}\xi)\xi$
C_{12} [14]	$-\eta(Z_1)\{\eta(Z_2)\Phi(\nabla_\xi \xi) + g(\nabla_\xi \xi, \Phi Z_2)\xi\} = \nabla_{Z_1}(\Phi)Z_2$
CNK [2]	Normal and $\nabla_{Z_1}(\eta)Z_2 + \nabla_{Z_2}(\eta)Z_1 = 0$
Nearly Kenmotsu [15]	$\nabla_{Z_1}(\Phi)Z_2 + \nabla_{Z_2}(\Phi)Z_1 = -\eta(Z_2)\Phi Z_1 - \eta(Z_1)\Phi Z_2$
Kenmotsu type [16]	$\nabla_{Z_1}(\Phi)Z_2 + \eta(Z_2)\Phi Z_1 = \nabla_{\Phi Z_1}(\Phi)\Phi Z_2$

for all $Z_1, Z_2 \in \mathcal{X}(M)$, where ∇ refer to Riemannian connection. Moreover, an ACM-manifold $(M^{2n+1}, \xi, \eta, \Phi, g)$ is called normal if $2N + \xi \otimes d\eta = 0$, where for all $U, V \in \mathcal{X}(M)$:

$$N(U, V) = \frac{1}{4}([\Phi U, \Phi V] + \Phi^2[U, V] - \Phi[\Phi U, V] - \Phi[U, \Phi V]),$$

is the Nijenhuis tensor of the structure tensor Φ (see [2]).

Definition 6. [6] An ACM-manifold $(M^{2n+1}, \xi, \eta, \Phi, g)$ is bearing an almost cosymplectic manifold if $d\Omega = 0$ and $d\eta = 0$, where

$$\Omega(Z_1, Z_2) = g(Z_1, \Phi Z_2) \quad \text{and}$$

$$2d\eta(Z_1, Z_2) = \nabla_{Z_1}(\eta)Z_2 - \nabla_{Z_2}(\eta)Z_1;$$

$$3d\Omega(Z_1, Z_2, Z_3) = \nabla_{Z_1}(\Omega)(Z_2, Z_3) + \nabla_{Z_2}(\Omega)(Z_3, Z_1) + \nabla_{Z_3}(\Omega)(Z_1, Z_2), \quad \text{for all } Z_1, Z_2, Z_3 \in \mathcal{X}(M).$$

Definition 7. [6] An ACM-manifold $(M^{2n+1}, \xi, \eta, \Phi, g)$ is bearing a LCAC-manifold if the ACM-manifold $(M^{2n+1}, \tilde{\xi}, \tilde{\eta}, \Phi, \tilde{g})$ is an almost cosymplectic manifold, where $\tilde{\xi} = \exp(\alpha)\xi; \tilde{\eta} = \exp(-\alpha)\eta; \tilde{g} = \exp(-2\alpha)g$, and α is a smooth function.

Definition 8. [17] An ACM-manifold M^{2n+1} is known as quasi-Sasakian manifold if $d\Omega = 0$ and M is normal.

Definition 9. [8] An RC-tensor of type $(3, 1)$ on a Riemannian manifold (N, g) is a tensor $R : \mathcal{X}(N) \times$

$\mathcal{X}(N) \times \mathcal{X}(N) \rightarrow \mathcal{X}(N)$ that defined by $R(Z_1, Z_2)Z_3 = ([\nabla_{Z_1}, \nabla_{Z_2}] - \nabla_{[Z_1, Z_2]})Z_3$, for all $Z_1, Z_2, Z_3 \in \mathcal{X}(N)$, where ∇ is Riemannian connection over N . Furthermore, the RC-tensor R of type $(4, 0)$ is given by the formula $R(Z_1, Z_2, Z_3, Z_4) = g(R(Z_3, Z_4)Z_2, Z_1)$, with $Z_4 \in \mathcal{X}(N)$.

Definition 10. [18] The associated space of G-structure for an ACM-manifold $(M^{2n+1}, \xi, \eta, \Phi, g)$ is a set of all A-frame $(x; Y_0 = \xi, Y_1, \dots, Y_n, Y_{\hat{1}}, \dots, Y_{\hat{n}})$, where $x \in M$, $Y_a = \frac{1}{\sqrt{2}}(\chi_a - \sqrt{-1}\Phi(\chi_a))$, $Y_{\hat{a}} = \frac{1}{\sqrt{2}}(\chi_a + \sqrt{-1}\Phi(\chi_a))$, $a = 1, 2, \dots, n$, $\hat{a} = a + n$ and $\{\chi_0 = \xi, \chi_1, \dots, \chi_n, \chi_{\hat{1}}, \dots, \chi_{\hat{n}}\}$ is a basis of $\mathcal{X}(M)$ which satisfies $g(\chi_p, \chi_q) = \delta_{pq}$, for all $p, q = 0, 1, \dots, 2n$.

Lemma 2. [19] Suppose that $(M^{2n+1}, \xi, \eta, \Phi, g)$ is an ACM-manifold and R its RC-tensor of kind $(4, 0)$ with components R_{pqrs} on the associated space of G-structure. Then the subsequent relations are satisfied:

- (1) $R_{pqrs} = -R_{qprs}$;
- (2) $R_{pqrs} = -R_{pqsr}$;
- (3) $R_{pqrs} = R_{rspq}$;
- (4) $R_{pqrs} + R_{psqr} + R_{prsq} = 0$,

where $p, q, r, s = 0, 1, \dots, 2n$.

Definition 11. [20] An ACM-manifold $(M^{2n+1}, \xi, \eta, \Phi, g)$ is said to be an almost $C(\lambda)$ -manifold if its RC-tensor R fulfill the following identity:

$$\begin{aligned} &g(R(Z_3, Z_4)Z_2, Z_1) \\ &= g(R(\Phi Z_3, \Phi Z_4)Z_2, Z_1) \\ &- \lambda \{ g(Z_1, Z_4)g(Z_2, Z_3) \\ &- g(Z_1, Z_3)g(Z_2, Z_4) \\ &- g(Z_1, \Phi Z_4)g(Z_2, \Phi Z_3) \\ &+ g(Z_1, \Phi Z_3)g(Z_2, \Phi Z_4) \}, \end{aligned}$$

where $Z_1, Z_2, Z_3, Z_4 \in \mathcal{X}(M)$, and $\lambda \in \mathbb{R}$.

Moreover, a normal almost $C(\lambda)$ -manifold is said to be $C(\lambda)$ -manifold.

The Components of Riemannian Curvature Tensor on the Associated Space of G-Structure

In this section, we review the ingredients of RC-tensor on the associated space of G-structure for certain classes of ACM-manifolds.

Theorem 1. [5] The components of RC-tensor of cosymplectic manifolds are given by: $R_{\hat{a}bc\hat{d}} = A_{bc}^{ad}$, and the other components are vanish or given by Lemma 2, or their conjugates, where A_{bc}^{ad} are smooth functions satisfy $A_{bc}^{[ad]} = A_{[bc]}^{ad} = 0$.

Theorem 2. [5] The components of RC-tensor of Sasakian manifolds are given by:

1. $R_{\hat{a}bc\hat{d}} = A_{bc}^{ad} - 2\delta_b^a \delta_c^d - \delta_c^a \delta_b^d$;
2. $R_{\hat{a}bcd} = \delta_{cd}^{ab} = \delta_c^a \delta_d^b - \delta_d^a \delta_c^b$;
3. $R_{\hat{a}ob0} = \delta_b^a$,

and the other components are vanish or given by Lemma 2, or their conjugates, where A_{bc}^{ad} are smooth functions satisfy $A_{bc}^{[ad]} = A_{[bc]}^{ad} = 0$.

Theorem 3. [5] The components of RC-tensor of Kenmotsu manifolds are given by:

1. $R_{\hat{a}bc\hat{d}} = A_{bc}^{ad} - \delta_c^a \delta_b^d$;
2. $R_{\hat{a}bcd} = \delta_{dc}^{ab} = \delta_d^a \delta_c^b - \delta_c^a \delta_d^b$;
3. $R_{\hat{a}ob0} = -\delta_b^a$,

and the other components are vanish or given by Lemma 2, or their conjugates, where A_{bc}^{ad} are smooth functions satisfy $A_{bc}^{[ad]} = A_{[bc]}^{ad} = 0$.

Theorem 4. [20] The components of RC-tensor of almost $C(\lambda)$ -manifolds are given by:

1. $R_{\hat{a}bcd} = \lambda \delta_{cd}^{ab}$;
2. $R_{\hat{a}ob0} = \lambda \delta_b^a$;
3. $R_{\hat{a}bc\hat{d}} - R_{\hat{a}cb\hat{d}} = -\lambda \delta_{bc}^{ad}$,

and the other components are vanish or given by Lemma 2, or their conjugates.

Theorem 5. [13] The components of RC-tensor of C_θ -manifolds are given by:

1. $R_{0\hat{a}b0} = F_{ac}F^{cb}$;
2. $R_{0ab0} = -F_{ab0}$;
3. $R_{0ab\hat{c}} = -F_{ab}^{\hat{c}}$;
4. $R_{\hat{a}bc\hat{d}} = A_{bc}^{ad} + F^{ad}F_{bc}$;
5. $R_{abcd} = -2F_{a[c}F_{|b|d]}$,

and the other components are vanish or given by Lemma 2, or their conjugates, where A_{bc}^{ad} are smooth functions satisfy $A_{bc}^{[ad]} = A_{[bc]}^{ad} = 0$, and $F^{ab}, F_{ab}, F_{ab0}, F_{ab}^{\hat{c}}$ are components of Kirichenko's fifth structure tensor F (see [16]) and their covariant derivatives respectively.

Theorem 6. [14] The components of RC-tensor of C_{12} -manifolds are given by:

1. $C_b^a - C^a C_b = R_{\hat{a}0b0}$;
2. $C^{ab} - C^a C^b = R_{\hat{a}0\hat{b}0}$;
3. $A_{bc}^{ad} = R_{\hat{a}bc\hat{d}}$,

and the disappeared components are vanish or given by Lemma 2, or their conjugates, where A_{bc}^{ad} are smooth functions satisfy $A_{bc}^{[ad]} = A_{[bc]}^{ad} = 0$, and C^a, C_a, C^{ab}, C_b^a are components of Kirichenko's sixth structure tensor G (see [16]) and their covariant derivatives respectively.

Theorem 7. [16] The components of RC-tensor over the manifolds of Kenmotsu type are seemed as follow:

1. $-\delta_c^a = R_{\hat{a}0c0}$;
2. $2A_{bcd}^a = R_{\hat{a}bcd}$;
3. $A_{bc}^{ad} - \delta_c^a \delta_b^d - B_{bc}^{ah} B_{bh}^d = R_{\hat{a}bc\hat{d}}$;
4. $2(-\delta_{[c}^a \delta_{d]}^b + B_{[cd]}^{ab}) = R_{\hat{a}b\hat{c}d}$;
5. $-B_{bc}^{ah} B_{cd}^{hd} + B_{cd}^{ad} = R_{\hat{a}b\hat{c}d}$,

and the other components are vanish or given by Lemma 2, or their conjugates, where A_{bc}^{ad} and A_{bcd}^a are suitable smooth functions and $B_{bc}^{ab}, B_{bc}^c, B_{cd}^{ab}, B_{cd}^{ad}$ are components of Kirichenko's first structure tensor B (see [16]) and their covariant derivatives respectively.

Theorem 8. [6] The components of RC-tensor of LCAC-manifolds are appeared as follow:

1. $2(A_{bcd}^a - \alpha_0 B_{b[d} \delta_{c]}^a + 4\alpha^{[a} \delta_{[c}^h] B_{d]hb}) = R_{\hat{a}bcd}$;
2. $2(2\delta_{[c}^b \alpha_{d]}^a - \delta_{[c}^a \delta_{d]}^b \alpha_0^2 + 2B^{hab} B_{hdc}) = R_{\hat{a}b\hat{c}d}$;
3. $A_{bc}^{ad} - 4B^{dah} B_{chb} + 4\alpha^{[a} \delta_{[c}^h] \alpha_{h]}^d - \delta_c^a \delta_b^d \alpha_0^2 + B^{ad} B_{bc} = R_{\hat{a}bc\hat{d}}$;
4. $2(2B_{[c|ab|d]} + B_{a[c} B_{d]b} - 2\alpha_{[a} B_{b]cd}) = R_{abcd}$;
5. $2(\alpha_{0[c} \delta_{d]}^a - 2\alpha^{[a} \delta_{[c}^h] B_{d]h} + B^{ab} B_{bcd}) = R_{\hat{a}0cd}$;
6. $A_b^{ac0} - \delta_b^c \alpha_0 \alpha^a + \alpha_b B^{ac} = R_{\hat{a}b\hat{c}0}$;
7. $2B_{cab} \alpha_0 + 2B_{cab0} = R_{abc0}$;
8. $-\delta_b^a \alpha_{00} - B_{cb} B^{ac} - \delta_b^a \alpha_0^2 - \alpha^a \alpha_b - \alpha_b^a + 2\alpha^{[a} \delta_b^c] \alpha_c = R_{\hat{a}0b0}$;
9. $2\alpha_0 B^{ab} + 2B^{bac} \alpha_c - D^{ab0} - \alpha^{ab} - \alpha^a \alpha^b = R_{\hat{a}0\hat{b}0}$,

and the other components are vanish or given by Lemma 2, or their conjugates, where A_{bc}^{ad}, A_b^{ac0} and A_{bcd}^a are suitable smooth functions, $B^{abc}, B_{abc}, B_{abcd}, B_{abc0}$ are components of Kirichenko's second structure tensor C (see [16]) and their covariant derivatives

respectively, B^{ab}, B_{ab}, D^{ab0} are the components of Kirichenko's third structure tensor D (see [21]) and their covariant derivatives respectively, $\alpha^a, \alpha_a, \alpha_0$ are the components of $d\alpha, \alpha_b^a, \alpha^{ab}$ are the components of $d\alpha^a$, and α_{00}, α_{0a} are the components of $d\alpha_0$.

Theorem 9. [4] The components of RC-tensor of quasi-Sasakian manifolds are given by:

1. $R_{\hat{a}bc\hat{d}} = A_{bc}^{ad} - 2B_b^a B_c^d - B_c^a B_b^d$;
2. $R_{\hat{a}b0c} = B_{bc}^a$;
3. $R_{\hat{a}b0\hat{c}} = B_b^{ac}$;
4. $R_{\hat{a}0b0} = B_c^a B_b^c$;
5. $R_{\hat{a}\hat{b}c\hat{d}} = 2B_{[c}^a B_{d]}^b$,

and the other components are vanish or given by Lemma 2, or their conjugates, where A_{bc}^{ad} are smooth functions satisfy $A_{bc}^{[ad]} = A_{[bc]}^{ad} = 0$, and $B_b^a, B_b^{ac}, B_{bc}^a$, are components of Kirichenko's fourth structure tensor E (see [16]) and their covariant derivatives respectively.

Theorem 10. [2] The components of RC-tensor of CNK-manifolds are given by:

1. $R_{\hat{a}bcd} = 2A_{bcd}^a$;
2. $R_{\hat{a}b\hat{c}d} = A_{bc}^{ad} - 2B_b^a B_c^d - B_c^a B_b^d + B_{bc}^{ah} B_{hd}^a$;
3. $R_{\hat{a}bc0} = -C_{bc}^a - B_{[b}^h B_{c]h}^a$;
4. $R_{\hat{a}0b0} = B_b^h B_h^a$;
5. $R_{\hat{a}b\hat{c}d} = 2(B_{[ac]}^{ab} + B_{[c}^a B_{d]}^b)$;
6. $R_{\hat{a}b\hat{c}0} = 2B_h^{[a} B_{c]}^b B_{h}^d$,

and the other components are vanish or given by Lemma 2, or their conjugates, where A_{bc}^{ad}, A_{bcd}^a are suitable smooth functions, B_b^a, C_{bc}^a are the components of Kirichenko's fourth structure tensor E and their covariant derivatives respectively, and $B_{bc}^{ab}, B_{bc}^c, B_{cd}^{ab}$ are the components of Kirichenko's first structure tensor B and their covariant derivatives respectively.

Theorem 11. [15] The components of RC-tensor of nearly Kenmotsu manifolds are given by:

1. $R_{\hat{a}bcd} = -\frac{2}{3} \delta_b^a F_{cd} + \frac{1}{3} \delta_c^a F_{db} + \frac{1}{3} \delta_d^a F_{bc}$;
2. $R_{\hat{a}b\hat{c}d} = A_{bc}^{ad} - C^{adh} C_{hbc} - \frac{1}{2} F^{ad} F_{bc} - \delta_c^a \delta_b^d$;
3. $R_{\hat{a}\hat{b}c\hat{d}} = 2C^{abh} C_{hcd} + F^{ab} F_{cd} - 2\delta_{[c}^a \delta_{d]}^b$;
4. $R_{\hat{a}\hat{b}\hat{c}\hat{d}} = C^{acdb} - \frac{1}{2} (F^{ab} F_{cd} + F^{ac} F_{db} + F^{ad} F_{bc})$;
5. $R_{\hat{a}0b0} = F^{ac} F_{cb} + \delta_b^a$,

and the other components are vanish or given by Lemma 2, or their conjugates, where A_{bc}^{ad} are suitable smooth functions, F^{ab} , F_{ab} are the components of Kirichenko's fifth structure tensor F , and C^{abc} , C_{abc} , C^{abcd} are the components of Kirichenko's second structure tensor C and their covariant derivatives respectively.

Theorem 12. [7] The components of RC-tensor of nearly cosymplectic manifolds are given by:

1. $R_{abcd} = -2B_{ab[cd]}$;
2. $R_{\hat{a}\hat{b}\hat{c}\hat{d}} = -2B^{\hat{a}\hat{b}\hat{h}}B_{\hat{h}\hat{c}\hat{d}}$;
3. $R_{\hat{a}0b0} = C^{ac}C_{bc}$;
4. $R_{\hat{a}\hat{b}\hat{c}\hat{d}} = A_{bc}^{ad} - B^{adh}B_{hbc} - \frac{5}{3}C^{ad}C_{bc}$,

and the other components are vanish or given by Lemma 2, or their conjugates, where A_{bc}^{ad} are suitable smooth functions, C^{ab} , C_{ab} are the components of Kirichenko's third structure tensor D , and B^{abc} , B_{abc} , B_{abcd} are the components of Kirichenko's second structure tensor C and their covariant derivatives respectively.

Conclusions

This paper collected the theories that determined the components of RC-tensors for 12 different classes of ACM-manifolds. So, the readers can be recognized the difference among these classes from the theorems in this paper. Then we concluded that the RC-tensor distinct according to its class.

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Conflict of Interest

The author declares no conflict of interest.

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مراجعة حول تنسر الانحناء الريماني لبعض فئات المنطويات المترية التلامسية تقريباً

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الخلاصة:

استعرض هذا البحث مركبات تنسر الانحناء الريماني على الفضاء المتعلق بالبنية G - لبعض فئات المنطويات المترية التلامسية تقريباً. الفئات التي تم دراستنا هي اثنتا عشرة فئة فقط والمعروفة بالاسماء منطويات كوسمبلكتك ومنطويات ساساكي ومنطويات كينموتسو ومنطويات G_0 - ومنطويات C_{12} - والمنطويات الطبيعية من النوع المعدوم ومنطويات كينموتسو التقريبي ومنطويات التحويل الكونفورمي المحلي للكوسمبلكتك تقريباً ومنطويات شبه ساساكي ومنطويات $C(\lambda)$ - تقريباً ومنطويات كوسمبلكتك التقريبي والمنطويات من نوع كينموتسو.

الكلمات المفتاحية: منطويات كينموتسو، منطويات $C(\lambda)$ ، منطويات ساساكي، منطويات كوسمبلكتك، منطويات اينشتاين.